



POD DRIVE EVO USER MANUAL

Pod Drive 1.0 / Pod Drive 3.0 / Pod Drive 6.0

Jan, 2021 Version 1.0

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Acknowledgement

Thanks for choosing ePropulsion products, your trust and support in our company are sincerely appreciated. We are dedicated to providing high-performance electric outboards, electric pod drives, sup/kayak motors, reliable lithium batteries and accessories.

Welcome to visit www.epropulsion.com and contact us if you have any concerns.

Using This Manual

Before use of the product, please read this user manual thoroughly to understand the correct and safe operations. By using this product, you hereby agree that you have fully read and understood all contents of this manual. ePropulsion accepts no liability for any damage or injury caused by operations that contradict this manual.

Due to ongoing optimization of our products, ePropulsion reserves the rights of constantly adjusting the contents described in the manual. ePropulsion also reserves the intellectual property rights and industrial property rights including copyrights, patents, logos and designs, etc.

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ePropulsion reserves the rights of final interpretation of this manual.

This manual is multilingual, in case of any discrepancy in the interpretation of different language versions, the English version shall prevail.

Symbols

The following symbols will help to acquire some key information.

 Important instructions or warnings

 Useful information or tips

Product Identification

Below picture indicates the serial numbers of Pod Drive Evo. Please note the position of the serial numbers and record them for access to warranty service and other after-sale services.

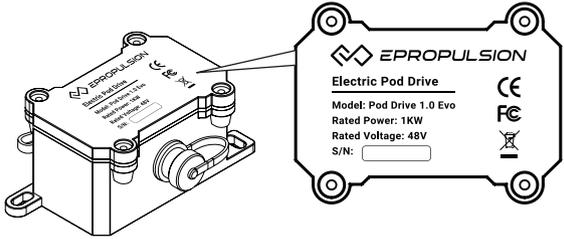


Figure 0-1

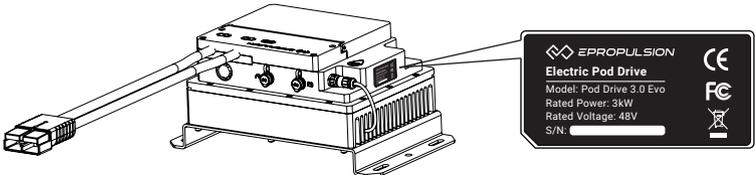


Figure 0-2

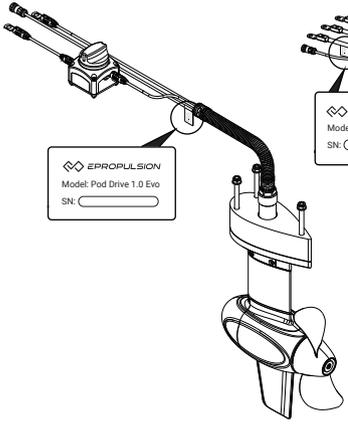


Figure 0-3

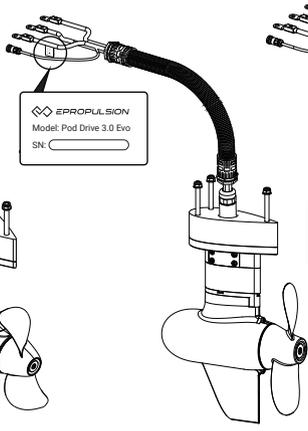


Figure 0-4

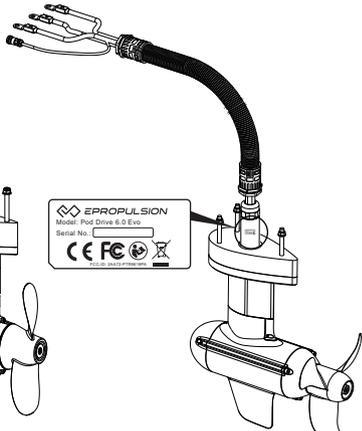


Figure 0-5

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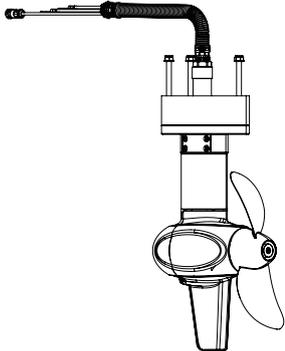
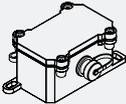
 13.3 Warranty Claim Procedures 43

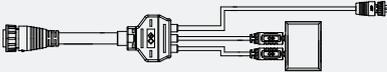
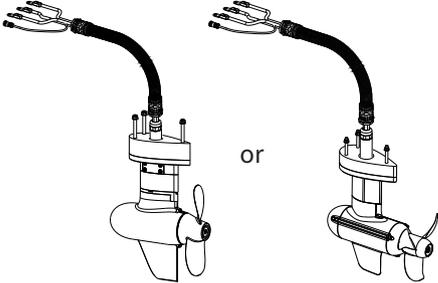
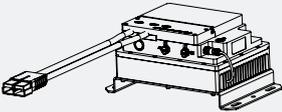
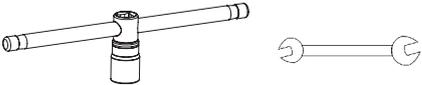
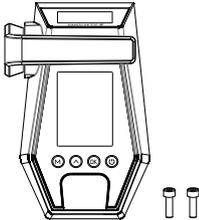
1 Product Overview

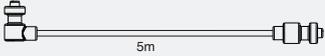
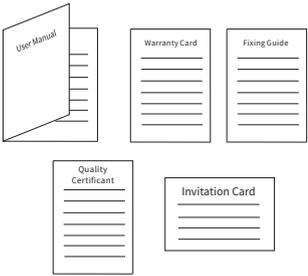
Pod Drive 1.0/3.0/6.0 Evo are the electric pod drive system of 1kW/3kW/6kW input power, controlled by either Evo Remote Control or Evo Side Mount Control. Pod is gaining increasing population among boat owners in recent decades. But available premium electric pod systems are rare. Electric pod drives are environment-friendly, clean and very efficient. This electric pod drive system is equivalent of 3hp/6hp/9.9hp, perfect for recreational small and medium sized boats such as sailboats and some motor boats.

1.1 In the Package

When you receive a set of Pod Drive Evo, unpack its package and check if all the items below are included in the package. If there is any loss or transport damage, please contact your dealer immediately.

Items	Qty./Unit	Figure
Pod Drive 1.0 Evo		
Pod Motor	1 Set	
Communication Module	1 Set	
Power Switch	1 Set	

Items	Qty./Unit	Figure
Connection Cable for Pod 1.0 Evo and Spirit Battery Plus	1 Set	
Pod Drive 3.0 Evo & Pod Drive 6.0 Evo		
Pod Motor	1 Set	
Driver Module	1 Set	
Wrench Set	1 Set	
Main Switch Cable	1 Set	
Shared by Pod Drive Evo		
Evo Remote Control (Purchased separately)	1 Set	

Items	Qty./Unit	Figure
Communication Cable	1 Set	
User Manual, Fixing Guide, Warranty Card, Invitation Card & Quality Certificate	1 Set	

- 💡 The Evo Remote Control need to be purchased separately.
- 💡 Other accessories such as batteries, charger, etc. appearing in this manual but not included in this package list require users to purchase them from ePropulsion authorized dealers.
- 💡 Save ePropulsion original package for transport and storage.

1.2 Parts and Diagrams

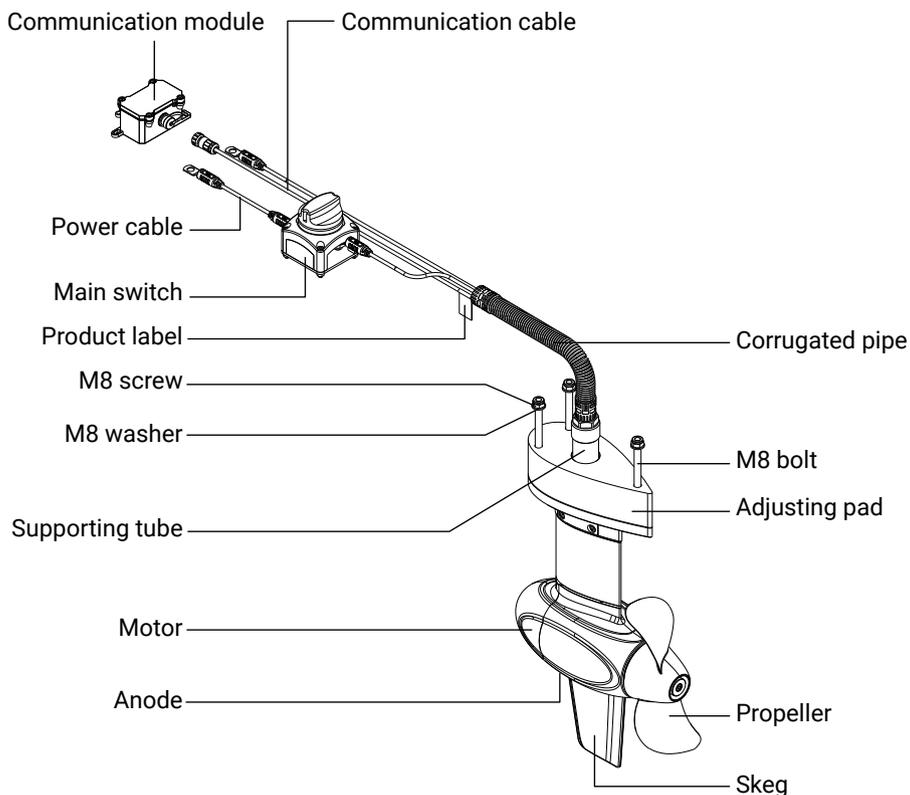


Figure 1-1 Pod Drive 1.0 Evo

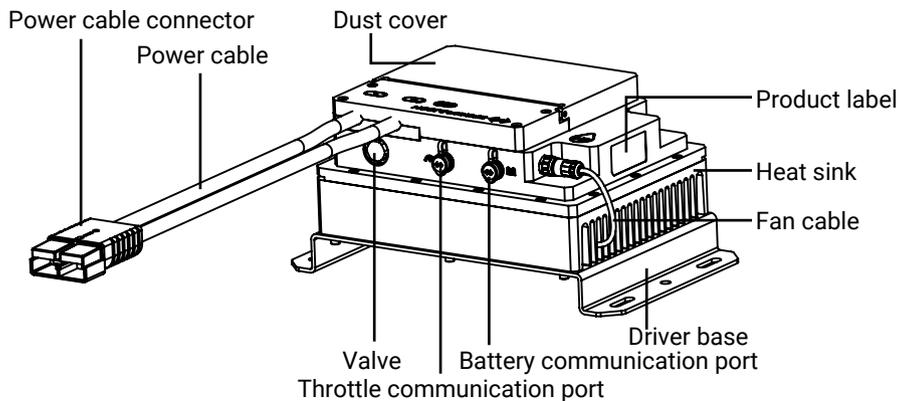


Figure 1-2 Pod Drive 3.0 Evo & Pod Drive 6.0 Evo Driver

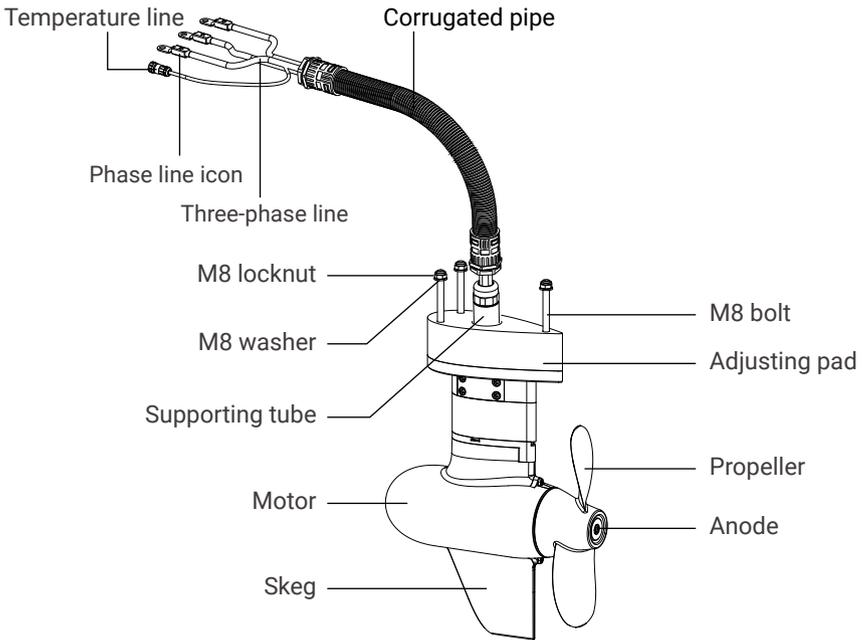


Figure 1-3 Pod Drive 3.0 Evo

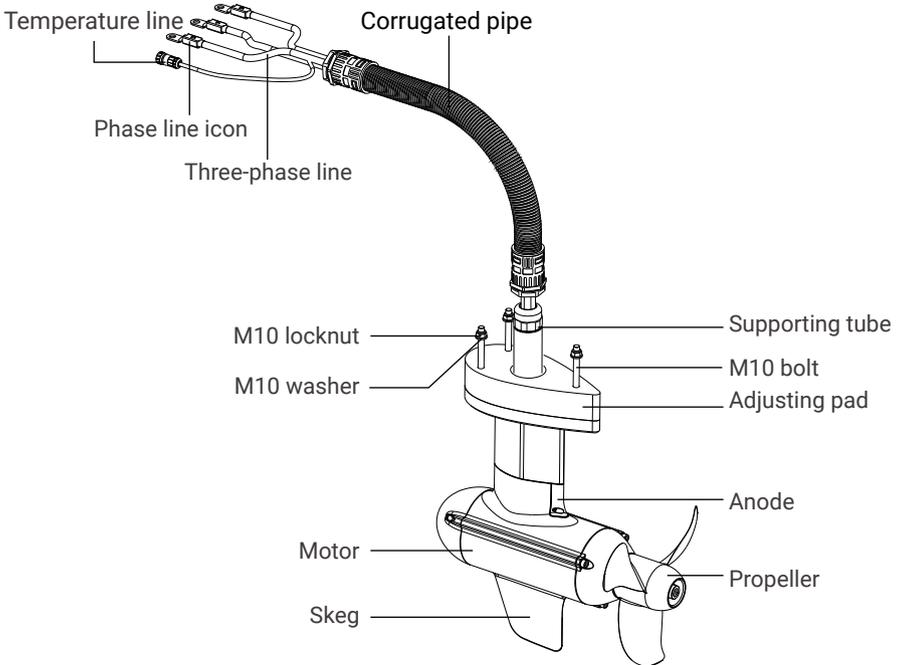


Figure 1-4 Pod Drive 6.0 Evo

1.3 Technical Data

	Pod Drive 1.0 Evo	Pod Drive 3.0 Evo	Pod Drive 6.0 Evo
Type	Electric		
Rated Voltage	48V		
Rated Current	20.8 A	62.5 A	125 A
Comparable Petrol Outboard	3 HP	6 HP	9.9 HP
Maximum Overall Efficiency	55%	51%	55%
Rated Rotation Speed (Forward)	1200 rpm	2300 rpm	1500 rpm
Control System	Remote Control / Side Mount Control		
Remote Communication	Wireless / Wired		
Communication Distance	Wireless ≤ 10 m / Wired ≤ 15 m		
Side Mount Communication	Wired		
Net Weight	6.2 kg	15.3 kg	31 kg
Propeller (Diameter / Pitch)	280 mm / 5.8"	260mm / 6.73"	320 mm / 8.73"

External Battery Requirement	
Type	Lead-acid Battery or Lithium Battery
Rated Voltage	48 V
Minimum Voltage	39 V
Maximum Voltage	60 V
Minimum Continuous Discharge Current	28 A
Internal Resistance	<100 mΩ

1.4 Declaration of Conformity

Object of the Declaration:

Product: Electric Outboard Motor

Model: Pod Drive 1.0 Evo, Pod Drive 3.0 Evo, Pod Drive 6.0 Evo

Company Name: Guangdong ePropulsion Technology Limited

Address: Room 201, Bldg.17A, 4th XinZhu Road, SongShan Lake District, Dongguan City, Guangdong Province, China

The object of the declaration is in conformity with the following directives:

EMC-directive	2014/30/EU
MD-directive	2006/42/EC
RED-directive	2014/53/EU

Applied Standards:

EN 55014-1:2017	EN 300328:2019
EN 55014-2:2015	EN 50663:2017
EN 61000-3-2:2014	EN 62368-1:2014+A1:2017
EN 61000-3-3:2013/A1:2019	EN 60204-1:2018
EN 301489-1:2019	EN ISO 12100:2010
EN 301489-3:2019	

This device complies with part 15 of the FCC Rules: Operation is subject to the following two conditions:

1. This device may not cause harmful interference and,
2. This device must accept any interference received, including interference that may cause undesired operation.

Signature: 

Shizheng Tao, Chief Executive Officer & Cofounder of
Guangdong ePropulsion Technology Limited

1.5 Important Notes

1. When choosing wireless remote control, ensure the top of the communication module/driver module is uncovered to avoid wireless signal attenuation.
2. Only adults who have fully read and understood this manual are allowed to operate this product. Read the full user manual carefully before operation, ePropulsion accepts no liability for any damage or malfunction caused by operations violating this manual.
3. Only boat owners who are familiar with their boats are allowed to use this pod system. For a newly bought boat, the boat owner should learn all aspects of the boat including how the boat behaves in different conditions and practicing controlling the boat before mounting and operating this pod system.
4. Before operation, familiarize yourself with all the functions and operations of this product. If there is more than one person onboard, make sure you are not the only one onboard who knows how to operate this pod drive system to help in case of an unforeseen emergency.
5. Follow boat builder's instructions to mount this product to your boat. It is suggested to have certified boat builders or professional installers to install this pod system to your boat. Never try to install the pod system on your own if you never have experience of mounting a pod to your boat before.
6. Check the weather before operation.
7. Watch the environment before operation. The rotating blades of pod drives are very dangerous and will hurt people or creatures. Do not operate the pod drive in areas with swimmers or bathers around.
8. If the pod drive system is the only power source of your boat, make sure batteries on board have enough power for your round trip. We recommend you to calculate distance and battery consumption.
9. Check before each trip if there are enough safety equipment including but not limited to enough life jackets, personal flotation devices, fire extinguishers, bells and whistles, communication equipment, and paddles, etc. Check available local boating safety requirement before operating.
10. If the pod drive strikes other objects in the water, please stop running immediately. Return to the nearest harbor and find your dealer for assistance.
11. If an error code displays and the pod drive malfunctions, please reset the throttle to zero position and cut the power off, then refer to the Warning Information to acquire the solution to the error.
12. Stop the pod drive immediately if someone falls into water.
13. Only run the pod drive while the propeller is under water.

2 Checking the Propeller

Before use, check the propeller and if necessary, eg. the original propeller is broken, change a new propeller.

Follow instructions in Figure 2-1~2-3 to assemble a propeller properly.

Assemble a propeller for Pod Drive1.0 Evo:

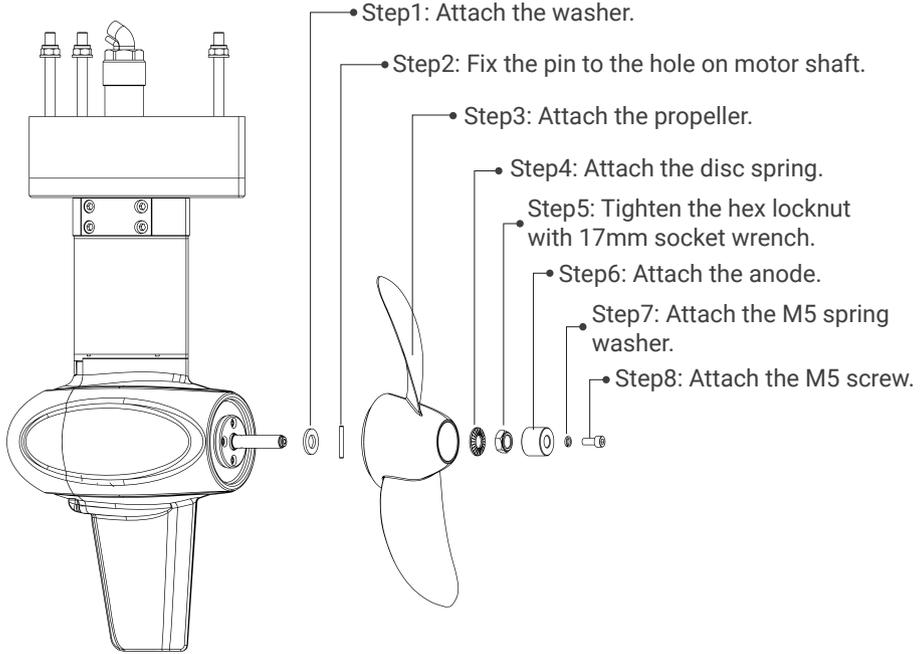


Figure 2-1

Assemble a propeller for Pod Drive3.0 Evo:

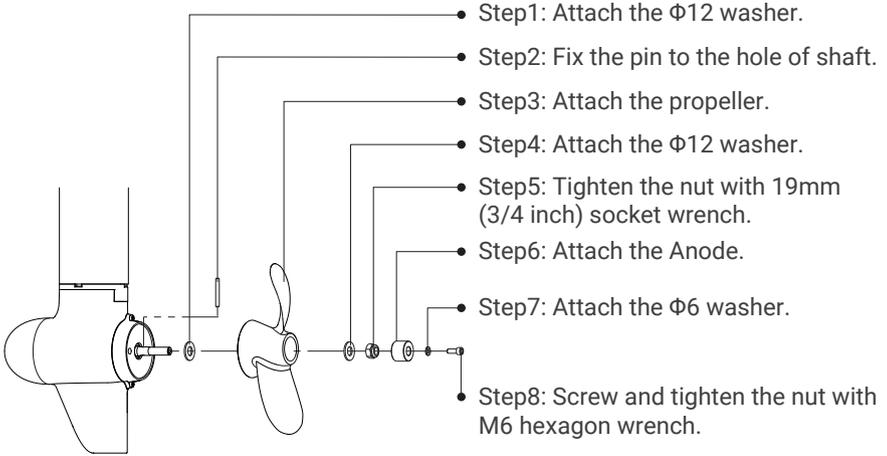


Figure 2-2

Assemble a propeller for Pod Drive 6.0 Evo:

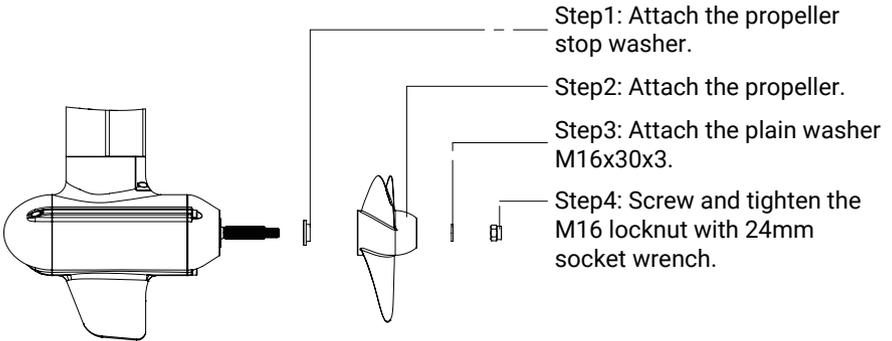


Figure 2-3

3 Mounting the Motor

Step 1: Drill four holes in the proper position through the hull bottom. The suggested dimensions of the four holes are shown below (please refer to the fixing guide):

Pod Drive1.0 Evo:

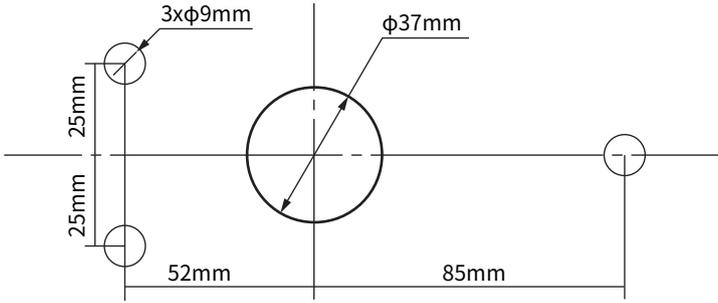


Figure 3-1

Pod Drive3.0 Evo:

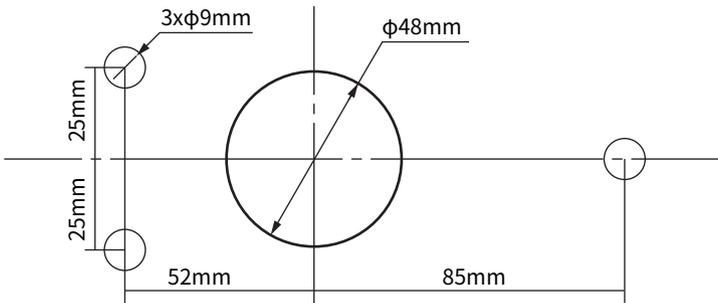


Figure 3-2

Pod Drive6.0 Evo:

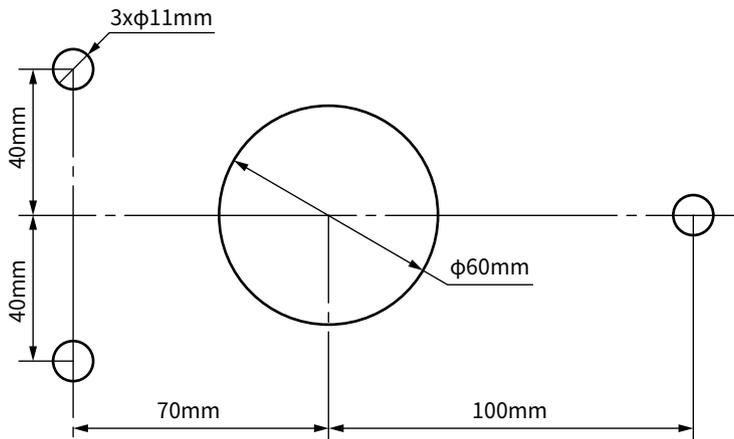


Figure 3-3

Step 2: Hold the pod motor and insert its three bolts (Pod Drive 1.0 & 3.0 are M8, Pod Drive 6.0 Evo is M10) and supporting tube into the holes from below the hull bottom. Then lock the each bolt from inside the boat by a plain washer and a nut (Figure 3-4).

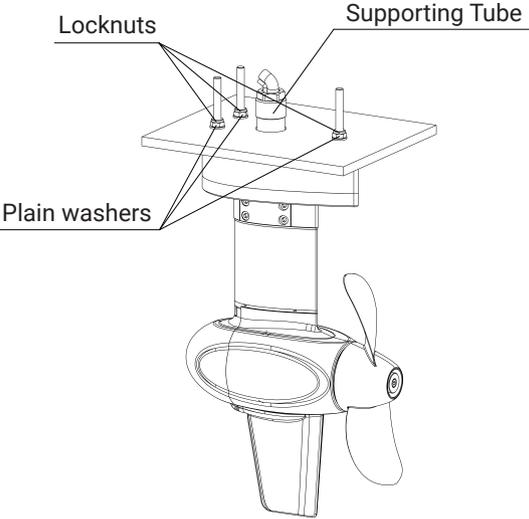


Figure 3-4

Pod Drive 1.0 Evo:

Step 3: Place the communication module on the proper position on the board and fix it with M4 screws.

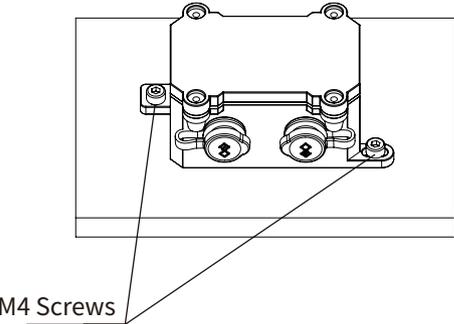


Figure 3-5

Step 4: Connect the power switch to the positive pole (red line) of the power cable of Pod Drive1.0 Evo.

Pod Drive 3.0 & 6.0 Evo:

Step 3: Check the three phase lines U-U1, V-V1, W-W1, put the three phase lines into the phase line clamp; fix the terminal on the driver with the hexagon screw M10 and washer (tightening torque 8 -10Nm); finally insert the temperature line into the corresponding connector and tighten it.

 Please check the U V W connection is correct, otherwise it may cause the motor to reverse.

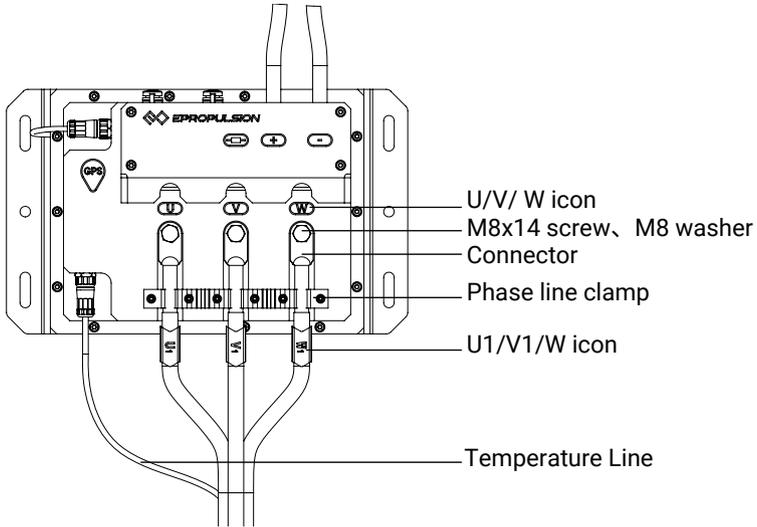


Figure 3-6

Step 4: Place the driver module on the proper position on the board and fix it with M8 screws (refer to figure 3-8 for the fixing holes).

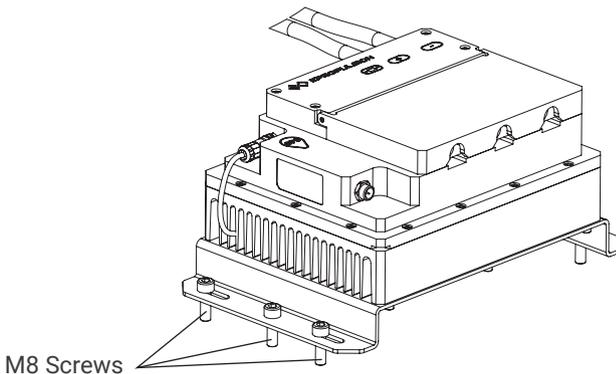


Figure 3-7

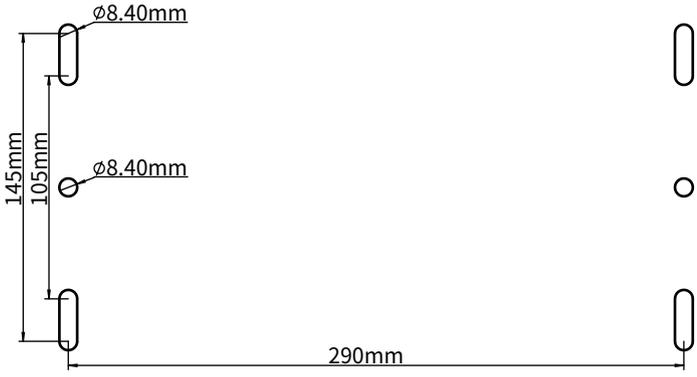


Figure 3-8

4 Connecting the Battery

4.1 Connecting a 48V Battery

Before connecting to a battery, make sure the main switch is off, and fix the battery and communication module/driver on the boat.

1. Connect the power cable of the pod drive to the battery.
2. If use ePropulsion batteries, please connect the battery and pod drive with a communication cable.

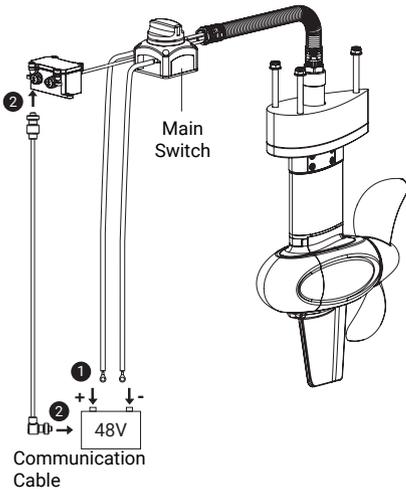


Figure 4-1

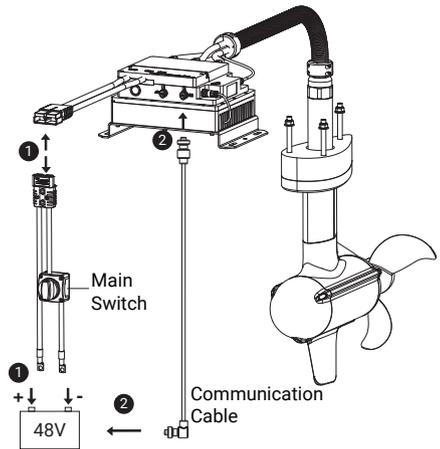


Figure 4-2

- ⚠️ Avoid battery short-circuit during connection.
- ⚠️ Do not short-circuit the main switch with other power supplies. The main switch should be mounted on the boat, and the back plate of the main switch should not be removed.
- ⚠️ Outboard motor will stop working once the power cable disconnects.
- 💡 Clockwisely rotate the main switch to power on the battery before use.
- 💡 Users can also enlarge the battery capacity by connecting multiple batteries in parallel.
- 💡 The main switch and power cable are connected by the fixing screws that may loosen after long-time use. Loosen screws will lead to poor contact, which may result in overcurrent or other errors. If this problem is discovered, open the back cover of the switch, and tighten the screws inside.

4.2 Connecting a SPIRIT Battery Plus (Only for Pod Drive 1.0 Evo)

If you use the Pod Drive 1.0 Evo and SPIRIT Battery Plus at the same time, please follow the steps below to connect SPIRIT Battery Plus and the communication module of Pod Drive 1.0 Evo:

1. Before connecting the battery and communication module, please fix the battery and communication module on the boat.
2. Connect the connection cable for Pod 1.0 Evo and Spirit Battery Plus (purchased separately) to the power cable of the machine.
3. Insert the power cable connector into the battery discharge connector, insert the communication cable connector into the connector of the communication module (as shown in the figure below), and then tighten the connector clockwise.

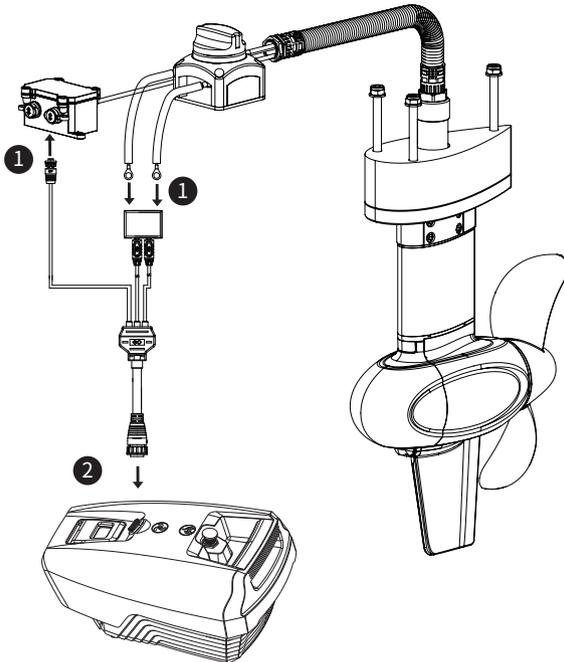


Figure 4-3

! Do not short-circuit the main switch with other power supplies. The main switch should be mounted on the boat, and the back plate of the main switch should not be removed.

5 Evo Remote Control

5.1 Display Panel

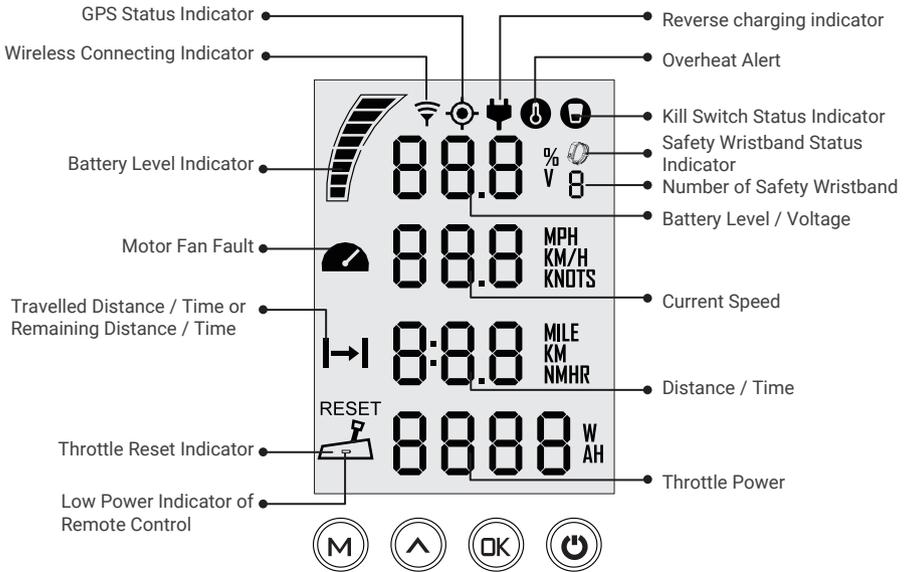
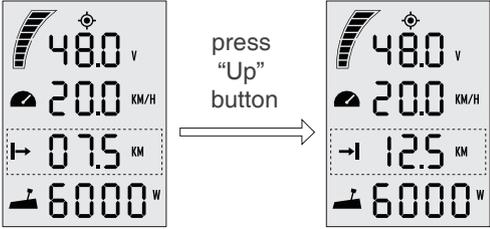
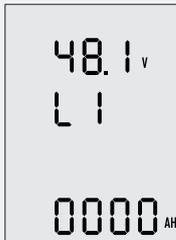


Figure 5-1

Buttons	Functions
 "Power"	<ol style="list-style-type: none"> 1. In power-off state, press and hold the power button to power on the remote control. 2. In power-on state, press and hold the power button to power off the remote control.
 "OK"	<ol style="list-style-type: none"> 1. On setting pages, press "OK" button to save the current settings and switch to the next item. 2. On setting pages, press and hold "OK" button, and the system will save your settings, the display will exit from setting page and return to the home page. 3. If home page displays or all characters display on the page, press "OK" button and hold 5s to enter the pairing page. 4. On home page, press "OK" button to switch between voltage V and battery percentage %.

Buttons	Functions
<p data-bbox="114 368 171 440">"Up"</p> 	<ol data-bbox="221 140 974 352" style="list-style-type: none"> 1. On any setting page, press " ^ " button to view options for current setting. 2. In power-on state, when home page displays, press " ^ " button and hold 10s to enter the throttle calibration page. 3. On home page, press " ^ " button to switch the travelling distance or time displaying icon between " → " and " → ". <div data-bbox="343 379 833 647" style="text-align: center;">  <p data-bbox="359 619 490 647">Main page 1</p> <p data-bbox="682 619 812 647">Main page 2</p> </div>
<p data-bbox="96 1038 187 1110">"Menu"</p> 	<ol data-bbox="221 683 974 1461" style="list-style-type: none"> 1. In power-on state, press and hold " M " button to enter the preference setting page. <div data-bbox="497 762 673 1002" style="text-align: center;">  <p data-bbox="469 1015 724 1043">Preference setting page</p> </div> 2. On preference setting page, press and hold " M " button to enter the battery setting page. <div data-bbox="497 1129 673 1369" style="text-align: center;">  <p data-bbox="487 1385 703 1414">Battery setting page</p> </div> 3. On any page, press " M " button to return home page.

 If users enter the page without setting any parameters, the current parameters displayed on the page will be saved as user parameters by default.

Icons	Functions	
	Battery level indicator	Indicating approximate battery level. The solid blocks stand for remaining battery.
	Battery level/voltage	Indicating accurate current battery level percentage/battery voltage, is configurable in preference setting page. For example: 100%: indicates current battery level. 48.0 v: indicates current battery voltage.
	GPS status indicator	<ul style="list-style-type: none">  Hidden: no satellite signal is received or GPS does not work.  Blink: GPS is connecting to satellites. Shown constantly: GPS is in use.
	Over-heat alert	<ul style="list-style-type: none">  Hidden: system temperature is in normal range.  Blink: system temperature is a little high and the maximum input power of motor has been lowered  Shown constantly: system is over temperature and the pod will stop working. The pod can't be started until the system temperature drops to a certain level.
	Kill switch status indicator	<ul style="list-style-type: none">  Hidden: kill switch is present and is working well.  Shown constantly: the kill switch is detached.
	Current speed	Displaying real time cruising speed. Set units (KM/H, MPH or KNOTS) in preference setting page.

Icons	Functions	
	Motor fan fault	 Blink: The motor fan has faults. Please contact the dealer to check the fan wiring.
	Distance/time display	Displaying real time travel distance/time. Set units (MILE, KM (kilometer) and NM (nautical mile)) in preference setting page. The time unit is HR (hour).
	Travelled distance/time or remaining distance/time	 : Remaining distance or time that the pod system can travel. Set units (MILE, KM (kilometer) and NM (nautical mile)) in preference setting page.  : Travelled distance or time.
	Throttle Power	Displaying real time input power to the system. A blinking "RESET" indicating the throttle should be reset to zero position.
	Wireless connecting indicator	Displaying the remote control is wireless connecting with pod drive.
	Hydro generation indicator	 Shown constantly: the hydro generation function is open.  Blink: the machine is charging the battery.
	Safety wristband connecting display	 Shown constantly: the safety is connecting with the remote control successfully.  Blink: there is a safety wristband to disconnect. The number indicates the number of safety wristbands connected to the remote control.

5.2 Charging

The remote control has an in-built lithium battery for power supply. The battery will be charged automatically under normal use: get charged by solar power or wired connection.

5.2.1 Charging by Solar Power

When the solar panel receives enough sunshine, it will generate electricity to charge the in-built lithium battery.

 Face the solar panel of the remote control toward sunlight to get better charging effect.

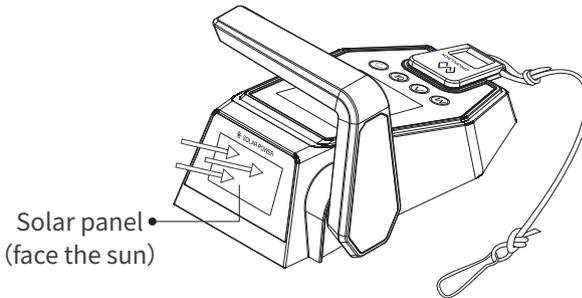


Figure 5-2

 Charging by solar power is recommended.

5.2.2 Charging by Wired Connection

If the remote control can't get enough solar power for a long time, the battery will run out. In this case, error code E60 (Figure 5-3) will display to remind you to charge the remote control.



Figure 5-3

In this case, charging by wired connection is faster.

Use a communication cable to connect the remote control and the communication module/driver. Then make sure the system battery is well connected to the pod drive and powered on.

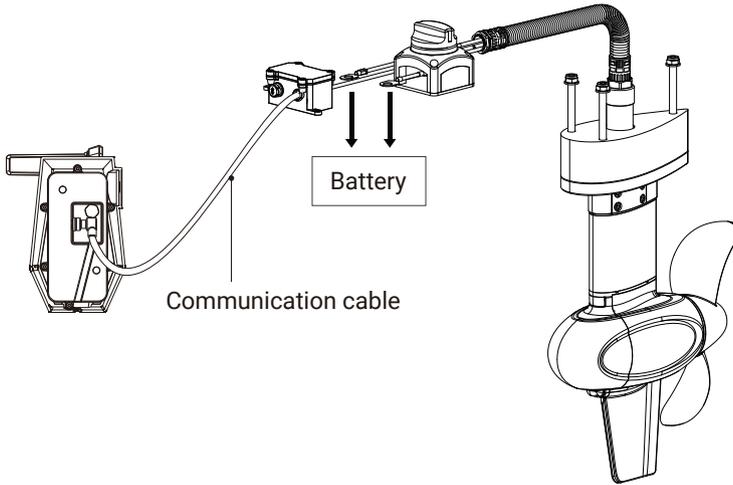


Figure 5-4

-  During long-term storage, ensure to charge the remote control every 6 months to avoid over-discharge.
-  Do not short-circuit the main switch with other power supplies. The main switch should be mounted on the boat, and the back plate of the main switch should not be removed.
-  After long-term storage, charge the remote control before use.
-  The communication cable is not included in this package. Please purchase one from your dealer if you choose this charging method. Once the communication cable disconnects, charging automatically stops and the running motor stops. Please restart the motor.

5.3 Power Adjusting

5.3.1 Power Adjusting for Evo Remote Control

 Please place the kill switch on the Evo remote control before operation.

The Evo Remote Control is mainly used to adjust the input power of the motor. When the battery is well connected and switched on, power on the Remote Control to start the pod drive, then slowly push the throttle forward position to increase the power. The maximum forward/backward power is shown below.

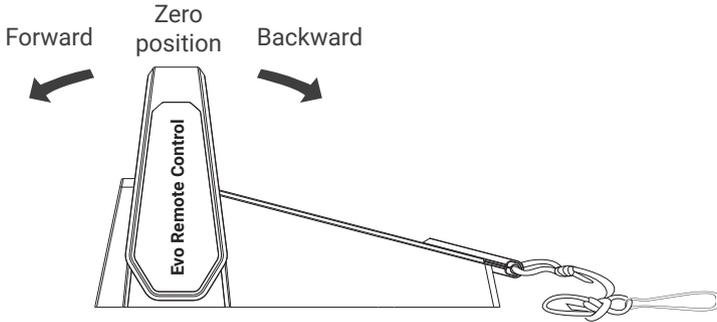


Figure 5-5

Model	Max forward power	Max backward power
Pod Drive1.0 Evo	1 kW	1 kW
Pod Drive3.0 Evo	3 kW	3 kW
Pod Drive6.0 Evo	6 kW	6 kW

 Before power on the Remote Control, please reset the throttle to neutral position.

 If you find a blinking “RESET” on the display panel, you are reminded to reset the throttle to neutral position.

 If you pull the throttle from the forward position to the backward position directly, the motor will first stop shortly, then start turning to the reverse direction.

5.3.2 Recalibration

If the error code displays as the figure 5-6, users should calibrate the throttle **strictly** as below steps.



Figure 5-6

Recalibration process	LCD Displaying
<p>Step1: Long press “^” button for 10s until “CAL FO” displays.</p>	
<p>Step2: Push the throttle to the maximum forward power position, then press “OK” button. “CAL ST” will display and “CAL” will be blinking.</p>	
<p>Step3: Pull the throttle to the middle (zero) position where you can hear a click sound, then press “OK” button, “CAL bA” will display and “CAL” will be blinking.</p>	
<p>Step4: Pull the throttle to the maximum backward power position, then press “OK” button. “CAL FO” will display and calibration is completed. A blinking “RESET” will display to remind you to reset the throttle to zero position.</p>	

Recalibration process	LCD Displaying
<p>Step5: Push the throttle to zero position and press the “M” button and return to the main page.</p>	

5.4 Use of Kill Switch

- Attach the kill switch and tie its lanyard to your wrist or life jacket.
- Stop the pod drive in emergency by detaching the kill switch.
- To run the motor again, first attach the kill switch then start the motor.

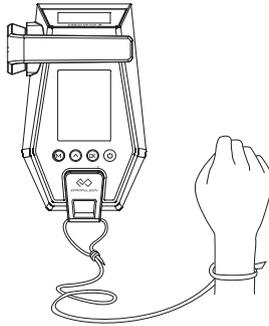


Figure 5-7

- ⚠ The kill switch generates magnetic field. Keep it 50cm / 20inches away from medical implants like pacemakers and magnetic cards (e.g. credit card) as well as other magnetic media.
- ⚠ The magnetic field of the kill switch may interfere with some electronic instruments. Keep it away from these electronic instruments.

5.5 Use of Safety Wristband

5.5.1 Pairing safety wristband with remote control

Press the "▲" and "OK" buttons and hold for a while to display the safety wristband icon and "SE". At this time, approach the safety wristband that needs to be paired, turn on the safety wristband, and the remote control displays the "SUC", indicating successful pairing. Keep in this interface and continue to press "OK" to pair the safety wristband continuously (the maximum number of pairs is 8). After completing the pairing, press the "M" button to return to the main page.

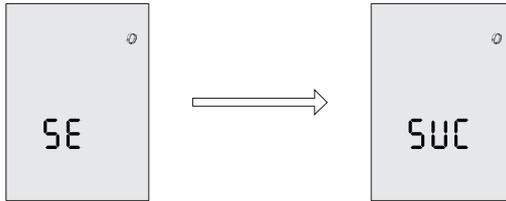


Figure 5-8

5.5.2 Man overboard protection

After the safety wristband and the remote control are paired, when the safety wristband falls into the water and the remote control is on, the remote control display will flash with a buzzing sound. The safety wristband icon flashes and the number of safety wristband decreases. At this time, you can continue to operate the machine by returning the throttle to zero position. The buzzer of the remote control will stop, but the display continues to flash. If you confirm that you need to cancel the alarm state, please restart the remote control or the disconnected wristband reconnects.

5.5.3 Emergency stop

After the safety wristband and the remote control are paired, when the remote control is in operation, short press the button of the safety wristband, the display of the remote control will flash with a buzzer. At the same time, the safety wristband icon flashes and the number of safety wristband displayed at the bottom decreases. At this time, you can continue to operate the machine by returning the throttle to zero position. The buzzer of the remote control stops, but the display continues to flash. If you confirm that you need to cancel the alarm state, please restart the remote control or short press the safety wristband after 5 seconds.

 When a wristband is disconnected or an emergency stop is performed, the stop command of other wristbands will not work until it returns to the normal state.

5.6 Pairing Remote Control with the Pod Drive

Before use please pair remote control with the pod drive. There are two methods to pair the remote control. Please choose one of the two methods and follow the steps to build new communication.

Method 1. Pairing without Communication Cable

Step1: Switch off system power and hold the remote control within 0.5m of the communication module/driver module.

Step2: Press and hold the “” button to switch on the remote control.

Step3: Ensure the wireless indicator is shown constantly on the home page.

Step4: Press “” button and hold **5s** to enter the pairing setting page (Figure 5-9).

On this page, you can find the blinking “Add” and “RUF”, and a countdown timer “060” (60s).



Figure 5-9

Step5: Switch on system power. Wait for them to get paired in seconds.

Step6: After pairing, the LCD panel will display as Figure 5-10 for 5s, then returning to home page automatically.



Figure 5-10

 If pairing fails within 60s, go back to **Step3** and try again.

Method 2. Pairing with Communication Cable

Step1: Switch off system power and the remote control.

Step2: Connect the remote control and the Communication module with a communication cable.

Step3: Switch on system power and the remote control. Wait for them to get paired in seconds. Pairing succeeds when home page displays.



No matter it is in wireless communication status or not, it will switch to wired communication status when you are pairing with a communication cable.



If the control system or the pod drive is replaced with a new one, the original wireless link will break and wireless communication failure will occur. The main page of the LCD panel on the Remote Control will display as below. In this case, users should conduct pairing again.

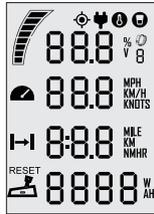


Figure 5-11

However, if the Remote Control and the pod drive are not replaced, but the LCD panel still displays like this, you should check and:

- 1) Make sure the Remote Control is not far from the outboard motor;
- 2) Make sure all the equipment involved is normally powered on.

If the Remote Control still displays like Figure 5-11 after check, it indicates an error has occurred. Please contact your dealer for repair.

5.7 Warning Messages

When the pod drive motor is running in abnormal conditions or out of order, a warning message with an error code will display on the LCD panel. Figure 5-12 is an example. Please find more error codes and corresponding solutions in the below table.



Figure 5-12

Code	Cause	Solution
E01	Battery voltage beyond operation range.	Replace a battery based on suggested operation specifications.
E02	Propeller may be blocked, causing motor overcurrent	Refer to Solution to E10.
	Motor fails or circuit board fails causing motor overcurrent	Try to turn off the main switch and wait for 10 seconds then turn on the switch again.
E06	The battery voltage level is too low.	Operate the motor at low power. Please charge the battery as soon as possible.
E10	Motor stall, which may be caused by blocked propeller	Turn off power, then clean up the things winding around the propeller. Test if the propeller can be rotated by hand before operation.
E11	The temperature of motor is too high.	Stop operating the pod drive and wait until the temperature falls within the normal operating temperature range.

Code	Cause	Solution
E12	The temperature of circuit board is too high.	Stop operating the pod drive and wait until the temperature falls within the normal operating temperature range.
E22	MCU Communication Abnormality	Please restart to see if the error disappears, if not, please contact your dealer for help.
E30	Throttle position sensor failure, should recalibrate the throttle position sensor.	Please refer to section <i>5.3.2 Recalibration</i> to recalibrate the throttle position sensor.
E56	Communication Error between pod drive and NAVY battery	Check if the communication cable between pod drive and NAVY battery is well connected, if yes, please restart the system.
E60	The remote control is running out of power.	Please connect the remote control to the pod by a communication cable. Please refer to section <i>5.2.2 Charged by Wired Connection</i> .
All characters display	The motor has no power.	Connect the battery to the pod drive and then turn on the main switch.
	Not paired	Please refer to section <i>5.6 Pairing Remote Control with the Pod Drive</i> .

 If the problem persists, please consult your ePropulsion authorized dealer for assistance.

6 Checklist before Use

1. Ensure the propeller is correctly and firmly mounted on the pod drive.
2. Ensure the pod drive is correctly and firmly mounted on the boat.
3. Ensure the remote control and steering wheel are installed in proper position before turning on the power.
4. Ensure the throttle travels smoothly with no obstacles.
5. Before connecting the battery, check and make sure there is no poor contacts or defects in cables.
6. Check and ensure the main switch is able to power on and off normally. After that, turn off the main switch.
7. Ensure the battery has enough power.
8. Ensure the remote control has enough power.



Make sure the power cable is dry before connecting it to the battery or powering on the system.

7 Starting the Pod Drive

1. Complete the check list.
2. Remove the kill switch from the remote control.
3. Push the throttle to zero position.
4. Connect the battery with the pod drive.
5. If use ePropulsion battery, turn on the main switch.
6. Press “” button to turn on the remote control.
7. Pair the remote control with the pod drive.
8. Carry out preference setting and battery configuration if necessary.
9. Tie the kill switch to your wrist or life vest, then attach the kill switch on the remote control.
10. Push the throttle slowly to start running.

8 Stopping the Pod Drive

It's recommended to stop the pod drive as the following procedures.

1. Return the throttle to zero position.
2. Wait until the motor stops, then detach the kill switch.
3. Press and hold the “” button until the remote control is switched off.
4. Turn off the main switch. If the pod drive is not connected to a SPIRIT battery, please also turn off the battery by pressing the power button.



The motor will also stop in any below situations.

1. Throttle is in zero position.
2. Kill switch is not placed in the correct position.
3. The power cable connected to the battery is loose.
4. The communication between the remote control and the pod drive is interrupted.
5. The connection between the battery and the pod drive is disconnected.
6. The system is malfunctioning (such as the motor is blocked or the battery voltage is too low).
7. The main switch is turned off.

9 Hydro Generation Function

Pod Drive Evo machines can drive the propeller to charge the battery (only the ePropulsion battery) through water flow.

The machine will enter the hydro generation state if the following conditions are met:

1. The remote control is set to turn on the hydro generation function (enabled by default).
2. The remote control is in the zero position.
3. The ePropulsion battery power is below 90%.
4. The machine will enter the hydro generation state after the boat speed is above 6km/h stably for 4 seconds.

When any of the following conditions occur, the hydro generation will be stopped:

1. The remote control is set to turn off the hydro generation function.
2. The remote control is in the forward/backward state (not in the zero position).
3. The ship is not traveling or traveling too fast (Pod Drive 1.0 Evo is higher than 35km/h, Pod Drive 3.0/6.0 Evo is higher than 45km/h).
4. The battery level is higher than 90%.

 The hydro generation function can be used only when connecting ePropulsion batteries.

Set up the hydro generation function

When the Evo remote control and the machine are successfully connected, and the Evo remote control and the machine are both on. Press the "M", "Λ" and "OK" buttons at the same time to enter the hydro generation setting interface. Then press "OK" to change the state of the hydro generation function (En means off, Dis means on).

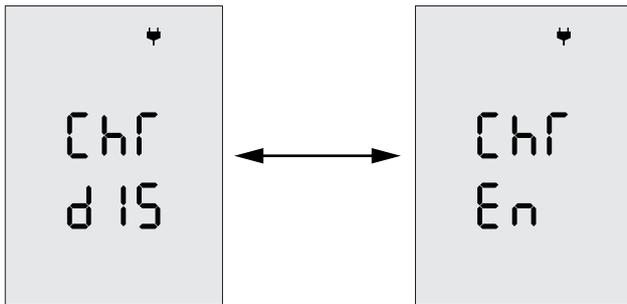


Figure 9-1

10 Maintenance

10.1 Propeller Maintenance

⚠ Ensure the battery is disconnected before each check, as a rotating propeller is dangerous.

⚠ Gloves are recommended to wear, in order to protect your hand from the sharp propeller edges.

Check the propeller based on the following tips, then refer to the *Chapter 2 Checking the Propeller* to replace a new propeller if necessary.

1. Check the propeller blades for wear broken and other damage.
2. Check the pin for wear and damage.
3. Check for water plants, fishing net or line twine around the propeller.

10.2 Replacing the Anode

Please refer to the figure below to replace a new anode if necessary.

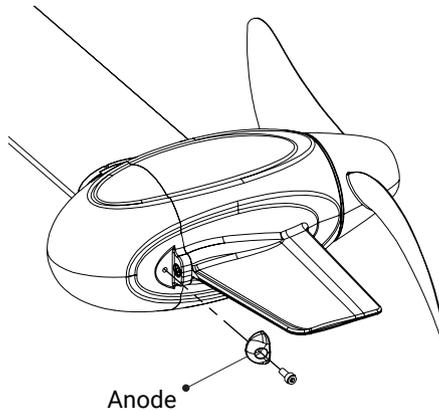


Figure 10-1 Replace Pod Drive1.0 Evo anode

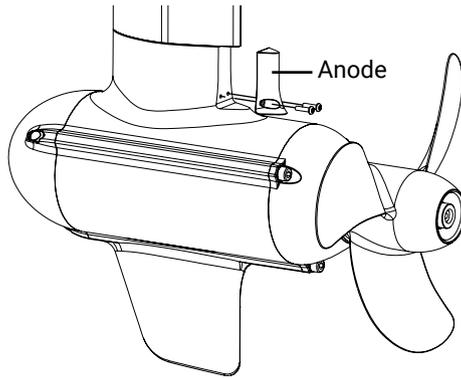


Figure 10-2 Replace Pod Drive6.0 Evo anode

11 Transport and Storage

Before long distance transport or long-term storage, please use ePropulsion original package to pack the pod drive.

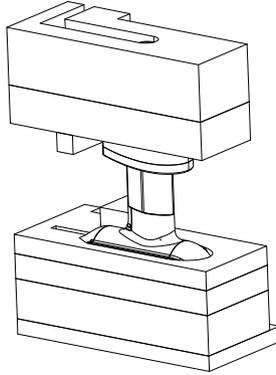


Figure 11-1

-  Make sure the pod drive gets adequate damping protection before transport and storage.
-  Store the pod drive in a well-ventilated and dry area without direct sun exposure.

12 Emergency Situations

12.1 Collision

If the pod strikes some object beneath the water, please follow below procedures.

1. Stop the pod immediately and then turn off the main switch.
2. Check the mechanical structure to see if there are damages.
3. Return to the nearest harbor or pier in low power.
4. Call your dealer to check the pod.

12.2 Low Battery Level

When the battery voltage is lower than 42V, the power will be limited by dropping voltage. When the battery voltage drops below 39V, the pod will stop automatically to prevent battery over-discharge. If this happens when the pod is far away from the shore, and there is an alternative battery, it's recommended to wait until the battery voltage rises 42V or above. When the voltage rises to a safe level, you can restart the pod system by restricting the power within 100W.

13 Warranty

The ePropulsion limited warranty is provided for the first end purchaser of an ePropulsion product. Consumers are entitled to a free repair or replacement of defective parts or parts which do not conform with the sales contract. This warranty operates in addition to your statutory rights under your local consumer law.

13.1 Warranty Policies

ePropulsion warrants its products to be free of defects in material and workmanship for a limited period for non-commercial purposes since the date of purchase. Once a fault is discovered, the user has the right to make a warranty claim under the ePropulsion warranty policy.

Product	Warranty Expiration Date
Pod Drive 1.0 Evo Pod Drive 3.0 Evo Pod Drive 6.0 Evo	Two years after the date of purchase.
Repaired/Replaced Parts	Three months since the date of maintenance. Notes: <ol style="list-style-type: none">1. If the three-month period overlaps with the original warranty period, the warranty against these replaced or repaired parts still expires two years after the date of purchase.2. If the three-month period exceeds the original warranty period, the warranty of the repaired or replaced parts expires by end of the third month since date of maintenance.



In order to validate the warranty, users are required to fill in the Warranty Card in the package in advance.



Keep the product label in an intact state and record the serial number on the label. Never tear the label off the product. An ePropulsion product without the original product label will not be applicable to warranty services provided by ePropulsion.



The warranty is valid only when the information is correct and complete.

 Free warranty is only validated upon the presentation of legal serial number, Warranty Card, and evidence of purchase from an authorized ePropulsion dealer.

 Valid date of purchase should be established by the first-hand purchaser with original sales slip.

 Free warranty is not transferable and will not be reissued.

13.2 Out of Warranty

Make sure the product is properly packed during delivery, the original ePropulsion package is recommended. If the product get further damage due to improper packing during delivery, the furtherly damaged part will be deemed as out of warranty coverage.

In addition, faults or damages caused by the following reasons are also excluded from warranty scope within the covered period:

- Any improper operation that contradicts the user manual.
- Accident, misuse, wishful abuse, physical damage overcharging, liquid damage or unauthorized repair.
- Dropping, improper care or storage.
- Used for commercial purposes.

 You should be noted that minor faults like normal wear and tear that pose no influence on the intended function of the product are also not covered by the warranty.

 Consumables are out of warranty scope.

13.3 Warranty Claim Procedures

If you find your product defective, you can make a claim to your dealer following below procedures:

1. Fill in Warranty Card correctly and completely in advance. Then make your warranty claim by sending it to your authorized ePropulsion service partner together with valid proof of purchase. Usually these documents are required when making a warranty claim: the Warranty Card, ex-factory serial number, and evidence of purchase.
2. Send the defective product to your authorized ePropulsion service point after

getting the confirmation. Note that the label should be kept intact. You can also deliver the product to your authorized ePropulsion dealer after getting confirmation.

3. The defective components or parts will be either repaired or replaced according to the diagnosis made by the ePropulsion authorized service partner.
 4. If your warranty claim is accepted, the equipment will be repaired or replaced free of charge. Note that any delivery cost incurred in the process is at your charge.
 5. After careful examination and confirmation by ePropulsion authorized dealer, the defective or faulty components will be repaired or replaced with brand new ones against the actual condition.
 6. In case your warranty claim be rejected, an estimated repair charge with round trip delivery cost will be sent for confirmation. ePropulsion authorized service point will conduct maintenance accordingly only after your confirmation.
-  If warranty expires, you can still enjoy maintenance services from authorized ePropulsion service partners with minimum maintenance charge.

Thanks for reading this user manual.

If you have any concerns or find any problems while reading, please don't hesitate to contact us. We are delighted to offer service for you.

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